YUXIN CHEN

PHD · CONTROL · ROBOTICS · MACHINE LEARNING

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SUMMARY

I build safe and agile embodied agents that intelligently perceive, interact with, and collaborate within the physical world while adhering to human values. My research emphasizes whole-body control of mobile robots, dexterous manipulation, and human-robot interaction, leveraging state-of-the-art advancements in reinforcement learning, generative models, optimization, and control.

EDUCATION

EDUCATION University of California, Berkeley	Berkeley, CA
PH.D. MECHANICAL ENGINEERING (CONTROL)	Aug 2022 – May 2027
Advisor: Prof. Masayoshi Tomizuka Misere: Mashing Learning Ontimization	
Minors: Machine Learning, Optimization	
University of Michigan, Ann Arbor M.S. ROBOTICS	Ann Arbor, MI Aug 2020 – May 2022
Advisor: Prof. Ram Vasudevan	Aug 2020 – May 2022
University of Michigan, Ann Arbor	Ann Arbor, Ml
B.S.E. AEROSPACE ENGINEERING (SUMMA CUM LAUDE)	Sep 2018 – May 2020
Minor: Computer Science	
Shanghai Jiao Tong University	Shanghai, China
B.S. MECHANICAL ENGINEERING	Sep 2016 – Aug 2020
Research Experience	
University of California, Berkeley	Berkeley, CA
GRADUATE STUDENT RESEARCHER	Aug 2022 – Present
Faculty member: Prof. Masayoshi Tomizuka Affiliation: Mechanical Systems Control (MSC) Laboratory & Berkeley Al Research (BAIR) & Berkeley DeepDi	rive (BDD)
University of Michigan, Ann Arbor	Ann Arbor, MI
GRADUATE STUDENT RESEARCHER	May 2020 – Jul 2022
Faculty member: Prof. Ram Vasudevan	
Affiliation: Robotics and Optimization for the Analysis of Human Motion (ROAHM) Laboratory	
University of Michigan, Ann Arbor Undergraduate Research Assistant	Ann Arbor, MI Oct 2018 – May 2020
Faculty member: Prof. Ella Atkins & Prof. Brent Gillespie	0012010 – May 2020
Affiliation: Autonomous Aerospace Systems (A2SYS) Laboratory & HAPTIX Laboratory	
Working Experience	
Robotics and Al Institute	Cambridge, MA
RESEARCH INTERN. (MENTOR: JIUGUANG WANG)	Mar 2025 – Present
Mitsubishi Electric Research Laboratories	Cambridge, MA
RESEARCH INTERN. (MENTOR: DEVESH JHA & DIEGO ROMERES)	May 2024 – Aug 2024
Zoox, Inc.	Foster City, CA
SOFTWARE ENGINEERING INTERN. (MENTOR: RICK ZHANG)	May 2021 – Aug 2021
Honda R&D Americas, LLC	Ann Arbor, MI
STUDENT MEMBER, MULTIDISCIPLINARY DESIGN PROGRAM (MENTOR: TYLER NAES)	Jan 2021 – Dec 2021

PUBLICATIONS

Journal

[J1] P. Ewen, A. Li, **Y. Chen**, S. Hong and R. Vasudevan, "These Maps are Made for Walking: Real-Time Terrain Property Estimation for Mobile Robots," *IEEE Robotics and Automation Letters (RA-L)*, vol. 7, no. 4, pp. 7083-7090, 2022.

Conference Proceeding

- [C7] Y. Chen, D. Jha, M. Tomizuka, D. Romeres, "FDPP: Fine-tune Diffusion Policy with Human Preference," 2025 IEEE International Conference on Robotics and Automation (ICRA), 2025. (acceptance rate: 38.7%)
- [C6] T. Zhang, Z. Wu, Y. Chen, Y. Wang, B. Liang, S. Moura, M. Tomizuka, M. Ding, W. Zhan, "Physics-Aware Robotic Palletization with Online Masking Inference," 2025 IEEE International Conference on Robotics and Automation (ICRA), 2025. (acceptance rate: 38.7%, Best Paper Award in Automation: 1/1606)
- [C5] Y. Xu*, Y. Chen*, J. Nie, Y. Wang, H. Zhuang, M. Okumura, "Advancing Cross-domain Discriminability in Continual Learning of Vision-Language Models," Advances in Neural Information Processing Systems (NeurIPS), 2024. (acceptance rate: 25.8%)
- [C4] Y. Chen, C. Tang, R. Tian, C. Li, J. Li, M. Tomizuka and W. Zhan, "Quantifying Interaction Level Between Agents Helps Costefficient Generalization in Multi-agent Reinforcement Learning," *Proceedings of the 1st Reinforcement Learning Conference* (*RLC*), 2024. (acceptance rate: 40%)
- [C3] Y. Chen, C. Tang, R. Tian, C. Li, J. Li, M. Tomizuka and W. Zhan, "Quantifying Agent Interaction in Multi-Agent Reinforcement Learning for Cost-efficient Generalization," *Proceedings of the 23rd International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, pp. 2201-2203, 2024. (Extended Abstract, acceptance rate: 45.1%)
- [C2] P. Ewen, J.P. Sleiman, Y. Chen, W.C. Lu, M. Hutter and R. Vasudevan, "Generating Continuous Motion and Force Plans in Real-Time for Legged Mobile Manipulation," 2021 IEEE International Conference on Robotics and Automation (ICRA), pp. 4933-4939, 2021. (acceptance rate: 43.6%)
- [C1] M. Romano, Y. Chen, O. Marshall, and E. Atkins, "Nailed it: Autonomous Roofing with a Nailgun-Equipped Octocopter," AIAA Aviation 2021 Forum, pp. 3211, 2021.

Preprints

- [P7] X. Zhu*, Y. Chen*, L. Sun*, F. Niroui, S. Le Cleac'h, J. Wang, K. Fang, "Versatile Loco-Manipulation through Flexible Interlimb Coordination," under review, 2025.
- [P6] Y. Chen*, J. Wei*, C. Xu, B. Li, M. Tomizuka, A. Bajcsy, R. Tian, "Reimagination with Test-time Observation Interventions: Distractor-Robust World Model Predictions for Visual Model Predictive Control," *under review*, 2025.
- [P5] S. Zhao, K. Yang, Y. Chen, C. Li, Y. Xie, X. Zhang, C. Wang, M. Tomizuka, "DexCtrl: Towards Sim-to-Real Dexterity with Adaptive Controller Learning," under review, 2025.
- [P4] P. Wang, X. Zhu, Y. Chen, C. Xu, M. Tomizuka, C. Li, "Residual Policy Gradient: A Reward View of KL-regularized Objective," under review, 2025.
- [P3] R. Jalayer, Y. Chen, M. Jalayer, C. Orsenigo, M. Tomizuka, "Testing Human-Hand Segmentation on In-Distribution and Out-of-Distribution Data in Human-Robot Interactions Using a Deep Ensemble Model," *under review*, 2025.
- [P2] S. Zhao*, X. Zhu*, Y. Chen, C. Li, X. Zhang, M. Ding, M. Tomizuka, "DexH2R: Task-oriented Dexterous Manipulation from Human to Robots," *under review*, 2024.
- [P1] Y. Chen*, C. Tang*, J. Wei, C. Li, R. Tian, X. Zhang, W. Zhan, P. Stone, M. Tomizuka, "MEReQ: Max-Ent Residual-Q Inverse RL for Sample-Efficient Alignment from intervention," *under review*, 2024.

TEACHING EXPERIENCE

University of California, Berkeley	Berkeley, CA
ADVANCED CONTROL SYSTEM I (MECENG 232) - GRADUATE STUDENT INSTRUCTOR	Fall 2024
Instructor: Prof. Masayoshi Tomizuka	
ADVANCED CONTROL SYSTEM II (MECENG 233) - GRADUATE STUDENT INSTRUCTOR	Spring 2024
Instructor: Prof. Masayoshi Tomizuka	
AI FOR AUTONOMY (MECENG 292B) - GRADUATE STUDENT INSTRUCTOR	Spring 2024
Instructor: Dr. Wei Zhan	
University of Michigan, Ann Arbor	Ann Arbor, Ml
University of Michigan, Ann Arbor Self-Driving Cars: Perception and Control (ROB 535) - Graduate Student Instructor	Ann Arbor, MI Fall 2021
SELF-DRIVING CARS: PERCEPTION AND CONTROL (ROB 535) - GRADUATE STUDENT INSTRUCTOR Instructor: Prof. Ram Vasudevan	,
SELF-DRIVING CARS: PERCEPTION AND CONTROL (ROB 535) - GRADUATE STUDENT INSTRUCTOR Instructor: Prof. Ram Vasudevan MOTION PLANNING (EECS 598) - COURSE ASSISTANT	,
SELF-DRIVING CARS: PERCEPTION AND CONTROL (ROB 535) - GRADUATE STUDENT INSTRUCTOR Instructor: Prof. Ram Vasudevan MOTION PLANNING (EECS 598) - COURSE ASSISTANT Instructor: Prof. Dmitry Berenson	Fall 2021 Winter 2021
SELF-DRIVING CARS: PERCEPTION AND CONTROL (ROB 535) - GRADUATE STUDENT INSTRUCTOR Instructor: Prof. Ram Vasudevan MOTION PLANNING (EECS 598) - COURSE ASSISTANT	Fall 2021

ACADEMIC SERVICES

 Journal Reviewer IEEE Robotics and Automation Letters (RA-L) 	2024 – Present
 Conference Reviewer International Conference on Learning Representations (ICLR) International Conference on Machine Learning (ICML) IEEE International Conference on Robotics and Automation (ICRA) IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) Reinforcement Learning Conference (RLC) Learning for Dynamics & Control Conference (L4DC) 	2025 2025 2024 – 2025 2023 – 2025 2025 2025
 Program Committee Co-organizer of IAVVC workshop on Scenario and Behavior Diversity in Simulation for Autonomous Vehicle Validation 	

Program Committee of ICRA workshop on Human-Centered Robot Learning in the Era of Big Data and Large Models
 2025

AWARDS AND SCHOLARSHIPS

2025	ICRA 2025 Best Paper Award in Automation,	, IEEE Robotics and Automation Society
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- 2025 Qualcomm Innovation Fellowship Finalist, Qualcomm Incorporated
- 2020 Outstanding Graduates of Shanghai (top 3%), Ministry of Education of Shanghai
- 2020 Capstone Design Gold Award (top 1%), Shanghai Jiao Tong University
- 2020 James B. Angell Scholar, University of Michigan
- 2019 Roger King Scholarship, University of Michigan
- 2018 Longey-SJTU Global Elite Scholarship, Shanghai Jiao Tong University
- 2017 Rongchang Science and Technology Innovation Scholarship, Shanghai Jiao Tong University
- 2017 Undergraduate Academic Excellence Scholarship, Shanghai Jiao Tong University