

# YUXIN CHEN

PHD · CONTROL · ROBOTICS · MACHINE LEARNING

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## SUMMARY

I build safe and agile embodied agents that intelligently perceive, interact with, and collaborate within the physical world while adhering to human values. My research emphasizes whole-body control of mobile robots, dexterous manipulation, and human-robot interaction, leveraging state-of-the-art advancements in reinforcement learning, generative models, optimization, and control.

## EDUCATION

### University of California, Berkeley

Berkeley, CA

#### PH.D. MECHANICAL ENGINEERING (CONTROL)

Aug 2022 – May 2027

- Advisor: Prof. Masayoshi Tomizuka
- Minors: Machine Learning, Optimization

### University of Michigan, Ann Arbor

Ann Arbor, MI

#### M.S. ROBOTICS

Aug 2020 – May 2022

- Advisor: Prof. Ram Vasudevan

### University of Michigan, Ann Arbor

Ann Arbor, MI

#### B.S.E. AEROSPACE ENGINEERING (SUMMA CUM LAUDE)

Sep 2018 – May 2020

- Minor: Computer Science

### Shanghai Jiao Tong University

Shanghai, China

#### B.S. MECHANICAL ENGINEERING

Sep 2016 – Aug 2020

## RESEARCH EXPERIENCE

### University of California, Berkeley

Berkeley, CA

#### GRADUATE STUDENT RESEARCHER

Aug 2022 – Present

Faculty member: Prof. Masayoshi Tomizuka

Affiliation: Mechanical Systems Control (MSC) Laboratory & Berkeley AI Research (BAIR) & Center for Humanoid Intelligence (HIC)

### University of Michigan, Ann Arbor

Ann Arbor, MI

#### GRADUATE STUDENT RESEARCHER

May 2020 – Jul 2022

Faculty member: Prof. Ram Vasudevan

Affiliation: Robotics and Optimization for the Analysis of Human Motion (ROAHM) Laboratory

### University of Michigan, Ann Arbor

Ann Arbor, MI

#### UNDERGRADUATE RESEARCH ASSISTANT

Oct 2018 – May 2020

Faculty member: Prof. Ella Atkins & Prof. Brent Gillespie

Affiliation: Autonomous Aerospace Systems (A2SYS) Laboratory & HAPTIX Laboratory

## WORKING EXPERIENCE

### Nvidia, Corp.

Santa Clara, CA

RESEARCH INTERN. (MENTOR: MARCO PAVONE & BORIS IVANOVIC)

Mar 2026 – Sep 2026

### Robotics and AI Institute

Cambridge, MA

RESEARCH INTERN. (MENTOR: JIUGUANG WANG)

Mar 2025 – Aug 2025

### Mitsubishi Electric Research Laboratories

Cambridge, MA

RESEARCH INTERN. (MENTOR: DEVESH JHA & DIEGO ROMERES)

May 2024 – Aug 2024

### Zoox, Inc.

Foster City, CA

SOFTWARE ENGINEERING INTERN. (MENTOR: RICK ZHANG)

May 2021 – Aug 2021

### Honda R&D Americas, LLC

Ann Arbor, MI

STUDENT MEMBER, MULTIDISCIPLINARY DESIGN PROGRAM (MENTOR: TYLER NAES)

Jan 2021 – Dec 2021

### ZF (China) Investment Co., Ltd

Shanghai, China

SOFTWARE DEVELOPMENT & TESTING INTERN. (MENTOR: YI ZHANG)

Jan 2018 – Mar 2018

## PUBLICATIONS

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(The superscript \* indicates equal contribution.)

### Journal

- [J4] K. Fang\*, **Y. Chen\***, X. Zhu\*, F. Niroui, L. Sun, J. Wang, "SAGA: Open-World Mobile Manipulation via Structured Affordance Grounding," *IEEE Robotics and Automation Letters (RA-L)*, 2026.
- [J3] S. Zhao\*, X. Zhu\*, **Y. Chen**, C. Li, X. Zhang, M. Ding, M. Tomizuka, "DexH2R: Task-oriented Dexterous Manipulation from Human to Robots," *IEEE/ASME Transactions on Mechatronics (T-MECH)*, 2025.
- [J2] R. Jalayer, **Y. Chen**, M. Jalayer, C. Orsenigo, M. Tomizuka, "Testing Human-Hand Segmentation on In-Distribution and Out-of-Distribution Data in Human-Robot Interactions Using a Deep Ensemble Model," *Mechatronics*, 2025.
- [J1] P. Ewen, A. Li, **Y. Chen**, S. Hong and R. Vasudevan, "These Maps are Made for Walking: Real-Time Terrain Property Estimation for Mobile Robots," *IEEE Robotics and Automation Letters (RA-L)*, 2022.

### Conference Proceedings

- [C14] Z. Huang, Y. Li, C. Zhang, R. Zhang, **Y. Chen**, G. Wang, X. Liu, M. Tomizuka, X. Ji, "3DWay: Generalizing Robot Manipulation via 3D Consistent Waypoints," *The 19th European Conference on Computer Vision (ECCV)*, 2026. (acceptance rate: 27.5%)
- [C13] F. Zhang, P. Wang, C. Li, Y. Li, **Y. Chen**, L. Feng, C. Xu, M. Tomizuka, B. An, "REAR: Test-time Preference Realignment through Reward Decomposition," *Forty-Third International Conference on Machine Learning (ICML)*, 2025. (acceptance rate: 26.6%)
- [C12] **Y. Chen\***, J. Wei\*, C. Xu, B. Li, M. Tomizuka, A. Bajcsy, R. Tian, "Reimagination with Test-time Observation Interventions: Distractor-Robust World Model Predictions for Visual Model Predictive Control," *2026 IEEE International Conference on Robotics and Automation (ICRA)*, 2026. (acceptance rate: 38.0%)
- [C11] S. Zhao, K. Yang, **Y. Chen**, C. Li, Y. Xie, X. Zhang, C. Wang, M. Tomizuka, "DexCtrl: Towards Sim-to-Real Dexterity with Adaptive Controller Learning," *2026 IEEE International Conference on Robotics and Automation (ICRA)*, 2026. (acceptance rate: 38.0%)
- [C10] G. Zhan, L. Tao, P. Wang, Y. Wang, Y. Li, **Y. Chen**, M. Tomizuka, S. Li, "Mean Flow Policy with Instantaneous Velocity Constraints for One-step Action Generation," *The Fourteenth International Conference on Learning Representations (ICLR)*, 2026. (acceptance rate: 28.2%, **Oral: 1.18%**)
- [C9] X. Zhu\*, **Y. Chen\***, L. Sun\*, F. Niroui, S. Le Cleac'h, J. Wang, K. Fang, "Versatile Loco-Manipulation through Flexible Interlimb Coordination," *2025 Conference on Robot Learning (CoRL)*, 2025. (acceptance rate: 35.8%, **Oral: 5.69%**)
- [C8] **Y. Chen\***, C. Tang\*, J. Wei, C. Li, R. Tian, X. Zhang, W. Zhan, P. Stone, M. Tomizuka, "MEReQ: Max-Ent Residual-Q Inverse RL for Sample-Efficient Alignment from intervention," *2025 Conference on Robot Learning (CoRL)*, 2025. (acceptance rate: 35.8%)
- [C7] **Y. Chen**, D. Jha, M. Tomizuka, D. Romeres, "FDPP: Fine-tune Diffusion Policy with Human Preference," *2025 IEEE International Conference on Robotics and Automation (ICRA)*, 2025. (acceptance rate: 38.7%)
- [C6] T. Zhang, Z. Wu, **Y. Chen**, Y. Wang, B. Liang, S. Moura, M. Tomizuka, M. Ding, W. Zhan, "Physics-Aware Robotic Palletization with Online Masking Inference," *2025 IEEE International Conference on Robotics and Automation (ICRA)*, 2025. (acceptance rate: 38.7%, **Best Paper Award in Automation: 10/4153**)
- [C5] **Y. Chen\***, Y. Xu\*, J. Nie, Y. Wang, H. Zhuang, M. Okumura, "Advancing Cross-domain Discriminability in Continual Learning of Vision-Language Models," *Advances in Neural Information Processing Systems (NeurIPS)*, 2024. (acceptance rate: 25.8%)
- [C4] **Y. Chen**, C. Tang, R. Tian, C. Li, J. Li, M. Tomizuka and W. Zhan, "Quantifying Interaction Level Between Agents Helps Cost-efficient Generalization in Multi-agent Reinforcement Learning," *Proceedings of the 1st Reinforcement Learning Conference (RLC)*, 2024. (acceptance rate: 40%)
- [C3] **Y. Chen**, C. Tang, R. Tian, C. Li, J. Li, M. Tomizuka and W. Zhan, "Quantifying Agent Interaction in Multi-Agent Reinforcement Learning for Cost-efficient Generalization," *Proceedings of the 23rd International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, 2024. (Extended Abstract, acceptance rate: 45.1%)
- [C2] P. Ewen, J.P. Sleiman, **Y. Chen**, W.C. Lu, M. Hutter and R. Vasudevan, "Generating Continuous Motion and Force Plans in Real-Time for Legged Mobile Manipulation," *2021 IEEE International Conference on Robotics and Automation (ICRA)*, 2021. (acceptance rate: 43.6%)
- [C1] M. Romano, **Y. Chen**, O. Marshall, and E. Atkins, "Nailed it: Autonomous Roofing with a Nailgun-Equipped Octocopter," *AIAA Aviation Forum*, 2021.

### Workshop

- [W4] X. Zhu\*, **Y. Chen\***, L. Sun\*, F. Niroui, S. Le Cleac'h, J. Wang, K. Fang, "Versatile Loco-Manipulation through Flexible Interlimb Coordination," *RSS 2025 Workshop on Whole-body Control and Bimanual Manipulation: Applications in Humanoids and Beyond (WCBM)*, 2025.

- [W3] **Y. Chen\***, J. Wei\*, C. Xu, B. Li, M. Tomizuka, A. Bajcsy, R. Tian, "Reimagination with Test-time Observation Interventions: Distractor-Robust World Model Predictions for Visual Model Predictive Control," *RSS 2025 Workshop on Out-of-Distribution Generalization in Robotics (OOD)*, 2025. (**Oral, Best Paper Finalist**)
- [W2] **Y. Chen**, D. Jha, M. Tomizuka, D. Romeres, "Adapting Diffusion Policies to Human Preferences via Reward-Guided Fine-Tuning," *ICRA 2025 Workshop on Safely Leveraging Vision-Language Foundation Models in Robotics: Challenges and Opportunities (Safe-VLM)*, 2025. (**Oral**)
- [W1] P. Wang, X. Zhu, **Y. Chen**, C. Xu, M. Tomizuka, C. Li, "Residual Policy Gradient: A Reward View of KL-regularized Objective," *ICRA 2025 Workshop on Safely Leveraging Vision-Language Foundation Models in Robotics: Challenges and Opportunities (Safe-VLM)*, 2025. (**Spotlight**)

### Preprints and Working Papers

- [P5] **Y. Chen**, H. Srikanth, N. Jew, M. Wu, P. Wang, J. Ren, M. Tomizuka, P. Xu, J. Xie, R. Tian, "CLIFT: Turning Gemini Robotics On-Device into Humanoid Specialists via Non-Invasive Closed-Loop Iterative Fine-Tuning," *under review*, 2026.
- [P4] A. Li\*, **Y. Chen\***, Z. Li, Z. Cao, J. Ren, M. Tomizuka, D. Shah, "Humanoid Navigation in Cluttered Environments with a Whole-Body Vision-Language-Action Model," *under review*, 2026.
- [P3] J. Cao\*, **Y. Chen\***, Y. Song, M. Tomizuka, C. Li, R. Tian, "TEXEDO: Test Time Scaling for Controller-Aware Language-Conditioned Humanoid Motion Generation," *under review*, 2026.
- [P2] J. Cao\*, **Y. Chen\***, M. Tomizuka, "CLAW: Composable Language-annotated Whole-body Motion Generation," *under review*, 2026.
- [P1] Z. Xu, J. Liu, **Y. Chen**, K. Keutzer, M. Tomizuka, C. Xu, C. Peng, "Rethinking Image-to-3D Generation with Sparse Queries: Efficiency, Capacity, and Input-View Bias," *under review*, 2025.

### AWARDS AND SCHOLARSHIPS

- 2026 **Qualcomm Innovation Fellowship Finalist**, *Qualcomm Incorporated*
- 2025 **Departmental Block Grant Fellowship**, *University of California, Berkeley*
- 2025 **ICRA 2025 Best Paper Award in Automation**, *IEEE Robotics and Automation Society*
- 2025 **Qualcomm Innovation Fellowship Finalist**, *Qualcomm Incorporated*
- 2020 **Outstanding Graduates of Shanghai (top 3%)**, *Ministry of Education of Shanghai*
- 2020 **Capstone Design Gold Award (top 1%)**, *Shanghai Jiao Tong University*
- 2020 **James B. Angell Scholar**, *University of Michigan*
- 2019 **Roger King Scholarship**, *University of Michigan*
- 2018 **Longey-SJTU Global Elite Scholarship**, *Shanghai Jiao Tong University*
- 2017 **Rongchang Science and Technology Innovation Scholarship**, *Shanghai Jiao Tong University*
- 2017 **Undergraduate Academic Excellence Scholarship**, *Shanghai Jiao Tong University*

### GRANTS

- 2026 **Nvidia Academic Grant Program**, *Nvidia*
- 2025 **Google-BAIR Commons**, *Google DeepMind*

### TEACHING EXPERIENCE

<b>University of California, Berkeley</b>	<i>Berkeley, CA</i>
ADVANCED CONTROL SYSTEM I (MECENG 232) - GRADUATE STUDENT INSTRUCTOR	<i>Fall 2024</i>
Instructor: Prof. Masayoshi Tomizuka	
ADVANCED CONTROL SYSTEM II (MECENG 233) - GRADUATE STUDENT INSTRUCTOR	<i>Spring 2024, Spring 2026</i>
Instructor: Prof. Masayoshi Tomizuka	
AI FOR AUTONOMY (MECENG 292B) - GRADUATE STUDENT INSTRUCTOR	<i>Spring 2024</i>
Instructor: Dr. Wei Zhan	
<b>University of Michigan, Ann Arbor</b>	<i>Ann Arbor, MI</i>
SELF-DRIVING CARS: PERCEPTION AND CONTROL (ROB 535) - GRADUATE STUDENT INSTRUCTOR	<i>Fall 2021</i>
Instructor: Prof. Ram Vasudevan	
MOTION PLANNING (EECS 598) - COURSE ASSISTANT	<i>Winter 2021</i>
Instructor: Prof. Dmitry Berenson	
INTRODUCTION TO AEROSPACE SYSTEMS (AERO 201) - COURSE ASSISTANT	<i>Fall 2019</i>
Instructor: Prof. Ella Atkins	

## ACADEMIC SERVICES

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### Journal Reviewer

- IEEE Robotics and Automation Letters (RA-L)

2024 – Present

### Conference Reviewer

- International Conference on Learning Representations (ICLR) 2025 – 2026
- International Conference on Machine Learning (ICML) 2025 – 2026
- Robotics: Science and Systems (RSS) 2025 – 2026
- Conference on Robot Learning (CoRL) 2025
- IEEE International Conference on Robotics and Automation (ICRA) 2024 – 2026
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2023 – 2025
- Reinforcement Learning Conference (RLC) 2025 – 2026
- Conference on Computer Vision and Pattern Recognition (CVPR) 2026
- European Conference on Computer Vision (ECCV) 2026
- Learning for Dynamics & Control Conference (L4DC) 2025

### Program Committee

- Co-organizer of IAVVC workshop on Scenario and Behavior Diversity in Simulation for Autonomous Vehicle Validation 2023
- Program Committee of ICRA workshop on Human-Centered Robot Learning in the Era of Big Data and Large Models 2025
- Program Committee for the 40th AAAI Conference on Artificial Intelligence (AAAI-26) 2025

## INVITED TALKS

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### Advancing Cross-domain Discriminability in Continual Learning of Vision-Language Models

- TwelveLabs Webinar Feb 2025

### Scaling Mobile Manipulation from Whole-body Coordination to Open-world Semantics

- Shenglanxueyuan Webinar Dec 2025
- Machine Vision and Intelligence Group at Shanghai Jiao Tong University Jan 2026
- Laboratory for Intelligent Decision and Autonomous Robots (LIDAR) at Georgia Institute of Technology Feb 2026

## MENTORSHIP

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<b>Yikuan Fang</b>	Undergraduate Student (Now a Master's student at CMU)
<b>Yiren Rong</b>	Undergraduate Student (Now a Ph.D. student at Duke University)
<b>Tianqi Zhang</b>	Undergraduate Student (Now a Ph.D. student at Tsinghua University)
<b>Jianglan Wei</b>	Undergraduate Student (Now a Master's student at CMU)
<b>Jingyuan Chen</b>	Undergraduate Student (Now a Master's student at University of Pennsylvania)
<b>Jianuo Cao</b>	Undergraduate Student at Nanjing University
<b>Hari Narayan Srikanth</b>	Undergraduate Student at University of California, Berkeley
<b>Nathan Alexander Jew</b>	Undergraduate Student at University of California, Berkeley
<b>Anqi Li</b>	Undergraduate Student at Peking University
<b>Zhaobo Li</b>	Master's Student at University of California, Berkeley
<b>Zhuo Cao</b>	Undergraduate Student at Tsinghua University
<b>Mengjie Zhao</b>	Undergraduate Student at Tsinghua University
<b>Menglin Wu</b>	Undergraduate Student at Xi'an Jiaotong University
<b>Jiakang Chen</b>	Undergraduate Student at Tsinghua University
<b>Shangbo Luan</b>	Undergraduate Student at Peking University
<b>Kaixiang Yao</b>	Undergraduate Student at Peking University